

Engineering Investigation of Information Integration Display (IID) Integration with Platform Systems

Final Report

Dale Blodgett
Rob Ens
Brian Monk
Danny Upson
Lockheed Martin Canada

Prepared By:
Lockheed Martin Canada
40 Highfield Park Dr., Suite 100
Dartmouth, NS B3A 0A3

Contractor's Document Number: 990002346
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Principal Author

Original signed by Dale Blodgett

Dale Blodgett

Principal Investigator

Approved by

Original signed by Francine Desharnais

Francine Desharnais

Head Maritime Decision Support

Approved for release by

Original signed by Calvin Hyatt

Calvin Hyatt

Chair DRP

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Abstract

This project investigated the feasibility and level of effort in acquiring the data required by the Information Integration Display (IID) system from current and near-future submarine systems. An IID Information Matrix is presented that describes 183 unique information types needed by the IID. For each of these, we identify potential submarine system source(s), recommend method(s) to make this information available to the IID, and list properties, both as needed by the IID and as available from the source. Recommendations for providing information to the IID include: i) developing an interface to CCS 876 Unicast data, ii) developing remote devices at four key locations, networked to the IID, to facilitate manual data collection and planning activities and provide the only feasible source of such data for the IID, iii) separate downloading of systems' "a priori" data (e.g., charts from SHINNADS Dual Monitor (SDM)) to the IID, iv) maintaining history data in the IID, and v) manual data entry into IID where appropriate. Based on the completed IID Information Matrix, we identify several issues and suggest appropriate solutions. Finally, we describe any outstanding issues and recommend the way ahead.

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1 Project Goals

1.1 Objectives

Defence Research and Development Canada (DRDC) Atlantic has conducted a Cognitive Work Analysis (CWA) for key Victoria Class Submarine (VCS) Control Room personnel, leading to the design of the Information Integration Display (IID) to bring relevant data together onto a single screen that is formatted to support Command decisions.

This project will investigate the feasibility, likely level of effort required and constraints of acquiring the data required by the IID system from the submarine information systems. The aim of this contract is to determine the scale of the integration work required to connect the developed IID display to current and near-future submarine information systems, primarily the Submarine Command and Control System (CCS 876), but secondarily the Central Surveillance System (CSS), Autopilot, Bathymetric Sampling System (BSS), and other systems as appropriate, to provide the required data to the display system.

Where required inputs are not readily available or are available from relevant sources, recommendations on the scope and feasibility of work required to obtain data will be determined.

1.2 Scope

The scope of this study is constrained by the following assumptions:

1. The information requirements of the IID are as identified in the Government Furnished Information (GFI) provided to Lockheed Martin Canada (LMC) by DRDC Atlantic, primarily references [1], [2] and [3].
2. In conjunction with the project Scientific Authority, it was decided to limit consideration of future information systems to systems already out for contract. As for soon to be obsolete systems, like the legacy Autopilot and legacy Surveillance System, LMC emphasized instead their planned replacements, the next generation Autopilot and CSS, respectively.
3. In determining the systems from which the required IID information is available, if multiple options exist, preference will likely be given to systems not yet implemented, where there may be the greatest likelihood of influencing system design to accommodate necessary changes to support the IID.
4. Throughout the report, we refer to SHINNADS Dual Monitor (SDM). Unless specified otherwise, we are not making any distinction between it and related system names like “SHINNADS” and “Electronic Chart Precision Integrated Navigation System (ECPINS)”.

2 Methodology

In order to fulfil the project objectives, the project investigations were conducted in the following primary tasks:

1. Task 1 – Identify the information types needed for the IID.
2. Task 2 – Investigate potential sources for the information types, and specify the properties of the information types both as used by the IID and as produced by the sources.
3. Task 3 – Based on the findings of the first two tasks, identify problems and recommend potential solutions.

The results of Tasks 1 and 2 were recorded in the “IID Information Matrix” described in more detail in Section 3.1.

The specific methodology used for each of these tasks is described in the following sub-sections.

2.1 Task 1 – Identify the Information Types Needed for IID

As a starting point for defining information types needed by the IID, we listed in the IID Information Matrix (see Section 3.1) all the “Information Requirement” items from the IID Area description tables in the IID Design Document (reference [1]).

These items were revised to provide more accurate definitions and descriptions. New items alluded to or implicit in the Design Document, which had been omitted from the IID Area description tables, were added.

The “Virtual Victoria Data Model” (reference [2]), “Assumptions and Specifications Matrix” (reference [3]), and a DRDC Atlantic demonstration to LMC of the prototype IID were used to augment and revise the list of information types.

Finally, the complete list of information types composed from the preceding steps included many redundant items. These were identified as such to create a list of unique information types. In the IID Information Matrix, each of the unique information types were numbered consecutively in the order listed; redundant information types were shaded blue and left unnumbered.

2.2 Task 2 – Investigate Sources and Properties of the Information Types Needed for IID

To the extent possible from the IID documentation made available to LMC (references [1], [2] and [3]), the properties of the information types as needed by the IID were entered in the IID Information Matrix. These properties included units, resolution, and allowed staleness. Originally, it had been planned to include “accuracy” of the information as required by the IID as one of the properties to consider. However, the IID design documents made available for this

study did not provide sufficient insight into this property to make it worth including in the IID Information Matrix. Furthermore, although “allowed staleness” was included in the IID Information Matrix, there was not much information on this property either in the IID design documents provided.

LMC identified potential source(s) of the various information types specified in the IID Information Matrix, determined if and how this information could be made available to the IID, and in the case of multiple sources for an information type, suggested the prioritization (Low, Medium, High) of the sources to utilize.

Finally, we populated the various fields in the IID Information Matrix regarding the properties of the information types as available from the source. The properties used are described in more detail in Section 3.1. Originally, it had been planned to include “accuracy” of the information produced by the source as one of the properties, but this was omitted because: i) there is often little or no information available on the accuracy of the source; ii) when information is available, it often tends to be Classified, whereas it was intended to keep the report Unclassified, and iii) some information types involve multiple systems (e.g., contact bearing, which could come from bow sonar, flank/towed array sonar, passive ranging sonar, periscope, or ESM), each of which would have a different accuracy.

In elaborating on the various properties on the IID information types, if the details of a property are not known or unavailable to LMC, it is marked as “Unk” (unknown). Sometimes, a particular property is not relevant to a particular IID information type, in which case it is marked as “N/A” (not applicable).

2.3 Task 3 – Identify Problems and Recommend Solutions

Based on the IID Information Matrix completed in Task 1 and Task 2, we identified various potential problems and observations, including:

1. Issues or complications related to the suggested source for an IID information type, including where no practical source is available.
2. Cautions, considerations or issues related to suggested methods to make the information available from a source to the IID, including the feasibility of these methods.
3. Incompatibilities between the IID and source properties related to an IID information type, e.g., where IID uses units for data different than the data is provided by the source.

These problems and observations are listed in Table 1. For each of these problems and observations, also shown in Table 1 is LMC’s recommended solution.

3 Results

Detailed information about each specific IID information type are provided in the IID Information Matrix described in Section 3.1. Recommended sources and methods to make the data available to the IID are described for each IID information type as part of the matrix. However, the general themes that emerged from the matrix regarding the sources for these IID information types are described in Section 3.2. Finally, Section 3.3 lists issues observed from the IID Information Matrix, and provides a recommended means to resolve these issues.

3.1 IID Information Matrix

The results of Task 1 and Task 2 investigations were recorded in an IID Information Matrix, as per Annex A.

In the first two columns of the IID Information Matrix:

1. “No.” is the number assigned to each unique information type.
2. “IID Info Definition” is the description of the information type identified in Task 1.

The properties of the information type as currently assumed or used by the IID are specified in the IID Information Matrix in the following columns:

1. “IID Display Ref (Area)” indicates the specific IID Display Area that uses the indicated information type.
2. “Units” specifies the units needed by the IID.
3. “Resolution” is the least significant value of the information that is needed by the IID.
4. “Allowed Staleness” is intended to be the elapsed time before a refresh of the information type is required, as expected by the IID.
5. The first “Comment” column addresses notes and issues about the information type pertaining to its use by the IID.

The properties of an information type in the submarine systems that can provide the information type are specified in the IID Information Matrix as follows:

1. “Submarine System” is a potential submarine system source for the information type. Primary consideration was given to systems that have feasible “Potential Method(s) to Transfer Info to IID”, as identified in the subsequent field in the IID Information Matrix.
2. “Publish/Subscribe Done” is specified as “Yes” if the identified system currently has a means to broadcast or make the data available for distribution, and “No” otherwise.

3. “Transmission Format” is the means by which the information type is transmitted, specified only when the previous “Publish/Subscribe Done” field is specified affirmatively.
4. “Potential Method(s) to Transfer Info to IID” are LMC’s suggestions for means whereby the indicated information type could be made available to the IID. LMC considered what it believed to be the most promising methods to provide data to the IID, with the least impact on systems and least requirement for engineering change.
5. “Time Between Data Refresh Within System” is the time between successive specifications of the data relevant to the information type as it is generated within the source system.
6. “Update Rate of Info Sent From System” is the rate at which data relevant to the information type is sent from the system.
7. “Units” specifies the units in which the information type is made available by the source.
8. “Resolution” is the least significant value of the information type data that is provided by the source.
9. “Security Designation” is the security level of the information type data provided by the source.
10. “Constraints” are special considerations, assumptions or limitations relevant to the information type that exist for the indicated submarine system source for that data.
11. “Prioritization of Multiple Systems” is LMC’s recommendation for the relative prioritization of the potential submarine system sources for the information type. Typically, this will be specified as “Low”, “Medium”, or “High”.
12. The second “Comment” column addresses notes and issues about the information type pertaining to the designated submarine system source for the information type.

In the IID Information Matrix, the purple text in the “IID Info Definition” column shows changes to, or new information types that were not listed in, the information requirement tables in the IID Design Document. The purple text in the first “Comment” column elaborates on the changes or additions made to the list of information types, or points out assumptions to be confirmed or questions to be answered by DRDC Atlantic. The blue shaded rows are information items from the IID Design document that were already covered by a similar information type elsewhere in the matrix, from one of the other IID display Areas. Each of the unique information types in the Information Matrix is assigned a number (the blue shaded rows, indicating redundant information types, are unnumbered).

3.2 General Comments on IID Information Sources

Sources specific to each IID information type are provided in the IID Information Matrix. The following are general observations and comments from consideration of all these IID information types.

1. As indicated in the IID Information Matrix, a substantial portion of the information types are not currently routinely broadcast or otherwise routinely receivable by IID. This includes sonars, ESM, and many other systems that pass data to CCS 876. To make information available directly from the systems that do pass information to CCS 876 would require significant engineering changes (ECs) to these individual systems. Alternatively, all this information can be provided from one source, CCS 876, with very minimal change. Specifically, CCS 876 has a “Unicast” capability already existing that provides real-time broadcast of all Data Gathering System (DGS) data generated by CCS 876. DGS data includes most of the relevant information from all these reporting systems. It is accessible from a simple Ethernet connection (to existing ports) on a CCS 876 console, and setup/specification at CCS 876 of the appropriate IP address at IID of the port to receive the data. The only required work to access the data is the development of an interface module at the IID that would receive the DGS data, interpret it (DGS data is sent in a defined message format, as per references [5], [6]), and parse it appropriately for IID.
2. Not all CCS 876 data is intrinsically Classified. However, in the context of an operational submarine, it is expected that in general CCS 876 data, particularly the Unicast data, will be Classified.
3. For the most part, there is currently no routine connection or access to repositories of historical data relevant to the historical information types (e.g., Nos. 72, 97, 113 in the IID Information Matrix). For example, some systems do accumulate history data, but typically extensive engineering changes to these systems would be required both to access and broadcast such data. Consequently, it is not currently practical to supply data for the historical information types (i.e., the complete record of all older data) directly from the submarine systems. Instead, it is recommended that the IID maintain a historical database of relevant data based on the accumulation of “real time” versions of such data that is provided from various sources to the IID.
4. There is a variety of “a priori” data (charts, tables, reference documents, threat sheets, etc.) that is the basis for data needed by various IID information types. Given the lack of current or easily implemented methods to provide most such “a priori” data directly from various submarine systems to IID, it is recommended to find alternative means to make such information available to IID. The most obvious solution is to simply separately load the “a priori” data into the IID as well as the relevant submarine systems. This would of course necessitate the development of IID modules to hold and read these databases, and format data to be used according to the same criteria and conditions as the systems on which the “a priori” data was originally installed. To some extent, this may involve replicating the same conditions, or knowledge of these conditions, as on the submarine system at the IID in order for the IID to use the same “a priori” data. In some cases, where the “a priori” data is hard-copy (e.g., paper charts, manuals), it may be necessary to convert this data to a format that can be used by the IID.
5. There are several IID information types that are used to define scale or parameters for IID display graphics, or control aspects of the IID displays (e.g., Nos. 19, 20, 26, 27, 135, 136, 181). These have been designated “IID Control Input” in the Source field in the IID Information Matrix. If these IID information types are intended to be dynamic and cannot be hard coded into the IID software, they would need to be done as manual inputs into the IID as

part of IID control. If the IID intends to vary the values for these information types based on observed conditions, then knowledge of some of the other routinely sent IID information types that characterize these conditions may be required. On the other hand, in most instances, these parameters remain at the total discretion of IID operators, and require no information from submarine systems.

6. There are several IID information types (e.g., Nos. 7, 21, 23, 28, 34–37, 54, 55, 58, 59, 62, 76, 81, 88–90, 101, 102, 120, 134, 137–139, 141, 143, 144, 146, 150) that in the IID Information Matrix have Submarine System designated as “Command Input” and Potential Method to Transfer Info to IID designated as “Manual Input”. They involve Command decisions and choices for information types like planned speed, depth, etc. that are not recorded electronically on any submarine system. Consequently, they would need to be manually entered into the IID. It is possible the collection/recording of this data could be accomplished via the “remote device” approach described in item 7.
7. There are many IID information types, specifically those in the IID Information Matrix that have Source specified as “Manual Data Collection” (e.g., Nos. 3–6, 10, 11, 100, 152–163, 167, 173, 174) or “Planning Inputs” (e.g., Nos. 121–132), which aren’t really tied to any current submarine system, and for which the only feasible method to make data available to the IID would be through manual input. However, we do believe it is possible to greatly improve the methods by which this data is collected or produced that would make it considerably easier for the IID to acquire this information. The current necessity for manual data entry and the quantity of information involved is overwhelming to be completed in just one location. We recommended the introduction of new “remote devices” (e.g., tablet, laptop) to collect and produce the desired data at the locations on the submarine where the relevant activities are most productively conducted. We see four primary functionalities/locations of use for these remote devices:
 - a. CO’s unit for Command inputs, which could be used in the CO’s cabin (with portability as required). In addition to providing Command with the tools to plan missions and schedule events, this remote access will allow the CO to relay night orders, broadcast routine and communication plans, navigational ETAs, mission orders, CO intentions, tactical primary/secondary objectives, and snort routines.
 - b. A unit for Nav O, Ops O, and trainee inputs, which could be used in the Wardroom. Much of the planning for inshore operations is currently done on paper charts. The remote device could serve as a more effective mission planning tool, allowing the CO and trainees to plan undisturbed, save and present their Command briefings, and make results available to IID as appropriate.
 - c. Chief and PO’s (C&PO’s) unit for mechanical, electrical, Combat Systems Engineer’s inputs, which could be used in the C&PO’s Mess. Currently, much of the information that is needed by the IID is recorded on “tally boards” with grease markers. Mechanical information such as fresh water, fuel supplies, and battery dips (which would be used to calculate and update battery endurance estimates based on current speeds) are recorded in logs outside of the C&PO’s Mess, which is also the ship’s damage control centre “HQ1”. Combat system defects, repairs, and system degraded implications could also be entered at this location and transmitted to the IID for display to Command. This would replace

paper logs/records as this information could be saved and backed up. In a damage control situation, access to appropriate damage control cards could be provided at the remote device. The IID in this situation could be updated from this unit, providing the CO with vital real time float, move, and fight data. As well, check lists such as Open Up for Dive, Smoke Clearance, and Damage Control Checks could also be entered at this location and displayed on the IID.

- d. A Sound Room unit for sensors, tactical and classification inputs, as well as RCN range prediction software. The remote entry device would produce a ray path plot and along with the COI's detection/the sub's evasion depth based on the current bathy could immediately be transmitted to the IID display. The unit would also allow for real time contact classification details to be directly passed to the IID and enhance the Sound Room record keeping abilities by allowing their data to be saved to a file. Other information that could be saved would eliminate the necessity for Sound Room contact and tape recording logs. COI threat sheets, next bathy, atmosphere monitoring, and EW danger levels would be entered at the Sound Room location.

These remote devices would be loaded with relevant “a priori” information and new applications to support specific activities heretofore largely manual and paper-based. For example, an ECPINS-like capability for chart data would likely be required on the CO and Wardroom units. These devices could be networked as appropriate (i.e., to the IID to exchange information). This scheme has the potential to make the IID a hub for planning results and a display point for what is currently numerous paper records.

Transitioning such activities to a remote device would make them more efficient, more accurate, allow a detailed, consistent, permanent record to be maintained, and provide a simple means to provide information needed by the IID but likely not otherwise easily available to it. The remote devices would also reduce the personnel traffic in the Control Room. Effort would be required to define and develop the applications for the appropriate remote devices, and define and implement the appropriate network connections to IID. However, the network requirements would be fairly minimal, and could be integrated with other required network infrastructure upgrades being planned for the submarines. Lockheed Martin has been involved in such network studies, as per reference [7]. Furthermore, there would be negligible impact on other current submarine systems, and no need for potentially complicated and costly ECs to these systems.

- 8. There did not appear to be any explicit mention of the use of Automatic Identification System (AIS) in the information types elaborated in reference [1], apart from how they could be used to contribute to general contact related information types (e.g., contact position). Currently on the submarine, AIS data is received, but not systematically integrated (apart from possible manual input) into the contact data processed by CCS 876. When used, a dedicated AIS view/layer is presented (e.g., on SDM). Consequently, in the definition of IID information types in the IID Information Matrix, a separate AIS IID information type was included, and it is recommended that it be incorporated in the Area 4 display as an independent layer. Since the AIS data is not integrated into CCS 876 contacts, it is probably not productive, and perhaps even misleading, for the IID to attempt to associate or fuse the AIS data with current CCS 876 contact data as part of the contact-related IID information types (for position,

course, speed, etc.). A suitable AIS interface would need to be developed for the IID, and IID displays appropriately updated to incorporate AIS data as suggested.

3.3 Analysis of IID Information Matrix

Table 1 below describes some of the principal issues (and their recommended solutions) from the IID Information Matrix. The IID Information Matrix should be examined directly for the discussion of issues relevant to each individual IID information type.

Table 1: Issues from Information Matrix and Recommended Solutions.

No.	Issues and Observations	Recommended Solution
1.	Geographic plots will need ownership and target course and speed data specified w.r.t. ground, while conventional tactical plots (e.g., like those on CCS) will require ownership and target course and speed specified w.r.t. the water mass in which the submarine resides (with the assumption that all platforms in the water mass experience the same movement of the water mass).	Area 4 related information types will be specified w.r.t. ground, while most of the remaining Area displays will use information types specified w.r.t. water mass.
2.	Accurate data for ownership course and speed w.r.t. ground, as well as latitude/longitude position, may be problematic when dived.	Ownership course and speed w.r.t. ground will rely on INS/GPS data. When GPS data is available (e.g., when submarine is at periscope depth or above), INS/GPS is quite accurate. However, when dived, GPS is not available, and only the course and speed w.r.t. water mass is precisely measured, while course and speed w.r.t. ground must be determined using estimates for speed and direction of the water mass (including from tables/charts of current). Consequently, INS data for position may be of limited accuracy. This is all part of the “Pool of Error” estimate integrated into SDM, which itself may evolve pending possible future upgrades to SDM.

No.	Issues and Observations	Recommended Solution
3.	Contact position on submarine systems is never shown in the context of geographic plots, i.e., in latitude/longitude plots (with the exception of when contacts are part of independently presented AIS data). Instead, contact position is shown w.r.t. ownship on what amounts to a locally flat Cartesian coordinate system.	To present CCS determined contact position data on a geographic plot, it would be necessary to add a module to IID that could convert CCS contact position data to latitude/longitude. Knowing ownship latitude/longitude (from ownship data) would allow orientation of the contact data within a geographic plot, and then suitable conversion of Cartesian flat-earth data on a contact to a curved coordinate system would be required to determine latitude/longitude of the contacts. However, it should be noted that when dived, the inherent inaccuracy of ownship data will also translate to similar inaccuracy in the converted contact position data.
4.	The information type for “Air Quality” (No. 3) was not specific about what aspects of air quality would be reported.	O2, CO2 and pressure levels can be routinely monitored on Analox; CO levels can be monitored by Draeger tubes during damage control.
5.	LMC noted several IID information types (Nos. 41, 83, 84, 159, 160) that were included in the Virtual Victoria Data Model (reference [2]) for which there was no relevant description in the IID Design Document (reference [1]).	These information types were included in the IID Information Matrix.
6.	The IID Design Document (reference [1]) tends to use “contact” and “COI” interchangeably for many of its information types, when in fact the COIs are a designated set of contacts, which are therefore a subset of all contacts.	Unless otherwise specified, we have treated those IID information types listed as “contact/COI” in the description as applying in general to a contact. Information type No. 146 is a Boolean that can be used to designate whether a given contact has been identified as a COI.
7.	The IID Design Document (reference [1]) tends to refer to information types as “relative bearing” (Nos. 93, 104, 105, 110) in instances that really involve what is designated as “true bearing” in sensors/CCS terminology.	These information types have been re-labeled as “true bearing”, and the sources that supply them also consider true bearing.

No.	Issues and Observations	Recommended Solution
8.	IID information type No. 140 deals with “Sensors holding contact”. However, there is no simple way to provide access to data directly from sensors. Furthermore, even the concept of a primary “reporting” sensor is not really used or maintained in CCS, apart from perhaps a verbal instruction to an operator to stop cutting contacts through to CCS. A similar issue is involved in the determination of “Previous Sensor Fixes” (No. 97).	DRDC should clarify the intended purpose of this information type. If it is sufficient to know what sensors are cutting data to CCS, this can be fairly easily interpreted from the proposed IID use of CCS 876 Unicast data by just monitoring what sensor data is being updated in the Unicast message stream. Any other interpretation requiring access directly to sensor data would be difficult to implement.
9.	Unlike the weapons status data that is available to CCS 876 via the Weapon System Data Bus, there is no equivalent broadcast of SSE status data. Consequently, there is no convenient method to convey SSE related data directly to IID.	SSE status/inventory will only be available to IID by manual input or manual data collection.
10.	There is an IID information type (No. 119) that represents the sonar waterfall display. At best, if the waterfall display video could be output from the sonar, there would be no way to present only the waterfall portion and exclude the menus that are also a part of the video display.	If the waterfall displays are required, it will probably be necessary to include the menus that are part of these sonar displays.
11.	No suitable source of altitude is currently available. Consequently, the “contact altitude” IID information type (No. 84) has no source for data in a submarine system.	At best, an operator or Command estimate could be made about contact altitude and manually input to IID.
12.	Contact behaviour is not analyzed or maintained systematically or in any automated manner by current submarine systems. Consequently, there is no source for IID information types “COI change behaviour” (No. 106) and “Contact/COI recent behaviour” (No. 114).	The raw contact data that can be used to perform the situation assessment to determine contact behaviour is potentially provided to IID (via CCS 876 Unicast). It is therefore feasible to develop modules in the IID that would perform the requisite behaviour analysis.

No.	Issues and Observations	Recommended Solution
13.	In CCS 876, tracks either are or are not included on the Threat Tote (up to 8 tracks can be assigned). No attempt is made to assign a quantitative threat value or relative ranking of the threats. Consequently, there is no source for IID information type “Threat level associated with COI” (No. 115) beyond a simple “threat/not a threat” designation for a contact.	Apart from whether or not a contact is on the CCS Threat Tote, any relative or quantitative evaluation of the threats would have to be done in an IID module using the CCS 876 Unicast data potentially available to IID. The only alternative would be Command designations about threat level that would be manually input to the IID.
14.	We noted minor differences in many of the information types between the units for data as needed by the IID and the units in which the data is provided by the system source. Common examples of the variations are metres vs. feet, Nautical Miles vs. yards, degrees vs. radians, and Knots vs. yards/sec.	These are simple unit conversions that should be coded as part of the IID interface modules that receive and process the data provided by the submarine system sources.
15.	IID information types No. 86 and 87 present data at the IID in hours, but the source information is measured as a percentage.	To present the required units for the data at the IID (i.e., in hours), in addition to the measured source data (specified as a percentage), it will be necessary to have a baseline value for total battery capacity to make the conversion to hours.
16.	No bathy and ray path plot history data is maintained for the IID in the available design documents.	We have proposed means to make bathy/ray path data available to the IID. It is recommended that a historical record of this data be maintained by the IID.

4 Conclusions

4.1 Summary of Findings

An IID Information Matrix was produced (see Annex A) that describes 183 unique information types needed by the IID. For each of these, we identified potential submarine system source(s), recommended method(s) to make this information available to the IID, and listed properties of the information types, both as needed by the IID and as available from the source.

The primary areas of new development to support making important information available to the IID are:

1. Provide an interface module, likely best suited as part of the IID software, which would receive, interpret and parse CCS 876 Unicast data. This interface is not a complicated programming problem (a related parser has been developed, as per reference [5], for other tasks), yet would make available to IID almost any data processed by CCS 876 (including most of the data passed to it from sensors and weapons).
2. Introduce several remote devices (e.g., tablet or laptop), and develop relevant applications for them, to provide data for IID information types that would require manual data collection or result from planning activities whose results would otherwise not be available to the IID.
3. Modify the IID software to read, store, and display/process as needed data corresponding to “*a priori*” information supplied to various submarine systems that is also needed by IID. This “*a priori*” data should be loaded onto IID separately when also loading on the originally intended submarine systems. In addition, it may be beneficial to convert data that currently exists only in a hardcopy format to an electronic format that could be used as needed on the IID, or the suggested remote devices.
4. Modify the IID software so that all historical data needed by the IID can be stored internally to the IID. Where there is a stated need for historical data, means have been suggested to make the real-time versions of this data available to IID. IID should be suitably modified to record, maintain, and access this data as needed.
5. Provide for manual entry into the IID of appropriate data, including most Command inputs, information that cannot be otherwise feasibly obtained from submarine systems, and data that is specifically intended as IID control inputs separate from any submarine system.
6. Introduce AIS data into the IID geographic display (Area 4) as a distinct layer, separate from other CCS based contact data that is displayed.

An analysis of the IID Information Matrix pointed out a variety of potential issues about the IID information types and how to make the data for them available to the IID. These issues are listed in Table 1. Also provided in this table is a recommended solution for each of these issues.

4.2 Discussion of Outstanding Issues

The following are issues that arose from this study, but for which there were no specific LMC recommendations to resolve:

1. Not much information was available in the IID reference documentation made available to LMC concerning the “Allowed Staleness” of the various information types as needed by the IID, so this field is largely designated as Unknown in the IID Information Matrix.
2. The IID information type properties of accuracy of the information type needed by the IID and accuracy of the information as provided by the source were eliminated from consideration due to lack of information in the available IID design documentation for the former, and because of the difficulty in accessing the information and Classified nature of the data when it is available for the latter. Consequently, no inconsistencies between accuracy needed by IID and accuracy available from source were examined. If this is critical information, then it will be necessary to acquire more detailed documentation on both the IID design, and performance specs and analysis on the submarine information sources.
3. No practical source of information is available for the following IID information types:
 - a. Contact altitude (No. 84 in the IID Information Matrix).
 - b. COI change behaviour (No. 106).
 - c. Contact/COI recent behaviour (No. 114).
 - d. Threat level associated with COI (No. 115).

For items b through d, if the IID adopts the recommended use of CCS 876 Unicast data, then all the raw data would be available to develop appropriate situation and threat assessment modules as part of the IID to make these types of evaluations possible as part of IID function.

4. Lack of documentation on SDM limits the insight LMC can provide on the use of SDM as a source for relevant IID information types, the methods by which information can be made available from SDM, and the properties of the SDM-related IID information types. However, LMC has sufficient fundamental understanding of SDM that our key recommendations and conclusions regarding sources and methods of availability for IID information types that could potentially involve SDM would not be substantially altered. In particular, items 4 and 7 in Section 3.2 present alternative approaches for supplying information to the IID that might otherwise have to be drawn from SDM.
5. For those IID information types that have the source listed as SDM, it should be recognized that there is no simple way to make SDM data electronically available to IID. In some cases, data thought of as SDM-related has already been alternatively sourced in the IID Information Matrix. For example:
 - a. “a priori” data held at SDM (e.g., charts) could alternately be loaded on IID when loading on SDM.

- b. External data read into SDM can simultaneously be read into IID, e.g., AIS.
- c. Some planning capabilities that use or produce information that could appear on SDM may be more suitably done on remote devices, as discussed earlier.

However, where there is no reasonable alternative to SDM for the IID to acquire data, it should be noted that there are immediate plans for a hardware upgrade to SDM. This may provide an opportunity for suitable ECs to SDM to make any necessary data available to IID. A further investigation would need to be conducted on the scope of changes to be made to SDM, and whether changes required for IID could be accommodated. In the interim, any information needed from SDM would likely have to be obtained via manual input. Fortunately, our other recommended courses of action for obtaining data related to the IID have minimized this requirement.

- 6. LMC reviewed high level documents for the CSS (e.g., reference [4]), but there was not much detail in the available documentation about new subsystems that might be integrated to the CSS and have data that may be relevant to the IID. Most of our projections about the CSS as a source of data and the means to provide it to the IID are based on our working knowledge of the current Surveillance System and the general information in the indicated reference documents. As more detailed design and interface specifications for the CSS come available, it may be feasible to update the methods to provide data to the IID for a few of the relevant IID information types. Regardless, in the IID Information Matrix, any information type for which the Source is specified as “CSS” will likely require additional design changes to the CSS to enable such information to be output to the IID.

4.3 Recommended Way Ahead

The following items are LMC’s primary recommendations for the way ahead in providing information from submarine systems to the IID:

- 1. Implement an interface to CCS 876 Unicast, likely as a module within IID software.
- 2. It was recommended that several “remote devices” (e.g., tablet, laptop) should be introduced to provide data for IID information types related to manual data collection, some planning activities, etc., as described in the IID Information Matrix. It is suggested that there probably should be a more general investigation of various submarine activities and processes that could benefit from various automated support tools on remote devices, for which the applications and devices needed for IID would be an important, but properly coordinated, subset. This would obviously benefit the IID in that data for IID information types that might not otherwise be available would be provided. However, it would simultaneously improve the capabilities and performance of the applications transferred to and performed on these remote devices, and thereby benefit overall VCS performance.
- 3. Develop a suitable interface for the IID to be able to receive AIS data, and update the IID displays to be able to incorporate the AIS data as suggested in Section 3.2 item 8.

4. Determine whether there are any indicated sources of “a priori” data (particularly those that may exist only in a hard-copy format) that should be converted to a format that is useable by the IID, and develop an appropriate interface for the IID to use this data.
5. LMC is currently implementing a significant upgrade to the Tactical Weapons Systems Trainer (TWS) in S17 at CFB Halifax, to be completed in FY13/14. The primary objective for the upgrade is to facilitate overall integration testing of current fitted systems with future Combat Systems ECs. Once the upgrade is complete, the TWS would be an ideal location to develop and validate the proposed methods to make information required by the IID available from submarine systems. This would hold especially for next generation systems that will be available for testing in the TWS prior to any other venue. Furthermore, the Submarine Division staff and students could/would readily provide feedback on concepts in aid of any formal project progression. It is recommended that in the short term (within the next FY) DRDC Atlantic undertake to produce prototype IID hardware and software to fit in the TWS, and develop the Unicast interface that will ultimately take data from the CCS 876 Tech Refresh System to be installed in the TWS Q2 14. At the same time, other suggested methods to utilize system sources available in the TWS can be investigated and developed as appropriate. This work could be done in parallel with the VCS backbone refresh currently being designed by Lockheed Martin.
6. Consideration could be given to the following three fitted sensor systems (with recommended upgrades in bold) for input to the IID through the Combat System LAN:
 - a. 2004 Sound Velocity (SV) Meter upper/lower sound (**A-D both outputs broadcast to CS LAN**).
 - b. Ownship Noise (OSN) Hydrophones discrete data (**A-D all outputs broadcast to CS LAN**).
 - c. 189 Cavitation Indicator (**A-D single output broadcast to CS LAN**).

Individually, these upgraded continuous outputs would provide significant platform self and situational awareness, presumably a goal of the IID. A simple combing algorithm could be developed to add considerably more value.

References

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- [3] Human Systems Inc. 2012. Assumptions and Specifications Matrix. Defence Research and Development Canada, Atlantic - Unpublished.
- [4] DND Canada. 2011. HMI Software Design Document Central Surveillance System (CSS). DND Canada.
- [5] Lockheed Martin MS2. 5 August 2010. Data Gathering System Analysis Tool (DGSAT) Version 3.4 User's Guide. Lockheed Martin INT-09-030.
- [6] Lockheed Martin MS2. 5 August 2010. Data Gathering System Format Document (Technical) For the Victoria Class Submarine Fire Control System. Lockheed Martin INT-09-031.
- [7] Lockheed Martin MS2. 19 September 2008. Victoria SFCS Network Study (Task 2) Report (Final). Contract W8482-071036/001/QF.

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Annex A IID Information Matrix File

The results of Tasks 1 and 2 were recorded in the IID Information Matrix. A description of the fields used to organize these results is provided in Section 3.1.

Info item is redundant (single)

Properties of Retained Information in the Submarine Systems in Which It Is Available											
Properties of Information for ID											
No.	ID Info Definition	ID Display Ref (Area)	Resolution	Allowed Staleness	Comment	Submarine System	Publsh/Subscribe Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Time Between Update of Info Within System	Update of Info Sent From System
1	DIG: Time of Day	Area 1	Units	Resolution							
2	DIG: Date	Area 1	Hours, Minutes, Seconds	Units							
3	Air quality	Area 2, Area 7	PPM	1	Used as a filter relating to the AIR QUALITY! Do you want to know if the atmosphere is in spec or do they want to know specific O2, CO2, CO, readings. The graphic shows a "PPM" reading but does not say what.	NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
4	Air quality Q2 level	Area 2, Area 7	PPM	1		NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
5	Air quality: CO2 level	Area 2, Area 7	PPM	1		NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
6	Air quality: CO level	Area 2, Area 7	PPM	1		NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
7	Air quality limit	Area 2	PPM	1		NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
8	Fuel Level (fuel remaining)	Area 2	PPM	1		NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
9	Fuel Level (low fuel limit)	Area 2	Percent	0.01	Provided by Comd. of a constant variable driven by operational commitments.	NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
10	Battery Endurance (current)	Area 2	Hours	0.1	Slow	NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
11	Battery endurance limit	Area 2	Hours	0.1	Slow	NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
12	Fish and Roll	Area 2	Fast	0.1		NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
13	Trim	Area 2	Degrees	0.1	State Change	NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
14	Oceananship:Comms:WaterMass:Currents	Area 2, Area 5, Rel Brdg	Degrees	0.1	Wet really mean full "ownship" course. Ownship bearing would only be relevant w.r.t. a reference point, which is very not practical.	NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
	Oceananship:Comms:WaterMass:Ground	-				NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
		(Area 4)			New. This is the course applicable to Area 2.	NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
		(Area 5)				NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.
		(Rel Brdg)				NTP x1	Yes	NMEA-0183 using Primary Method: CCS Ethernet Switch (A1/A5) located on the back of CCS Consoles. (A1/A5) Secondary Method: Retrieve data from LAN1 Ethernet Switch located tied to SDR.	CCS	No	CCS UNICAST - Ownership Message.

Properties of Information for ID										Properties of Required ID Information in the Subsuming System(s) in Which It Is Available							
No.	ID Info Definition	ID Display Ref (Area)	Units	Resolution	Allowed States/ness	Comment	Submarine System	Publsh/Subscribe Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Time Between Update Rate of Info Sent From System Within System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment
15	Planned Route/wpln: Planned Home:	Area 2, Area 6 (Planned route/pays), (Planned route/area), (Planned route)	Degrees	Urnk	Urnk	Should be labelled Planned "Course" NOT "Bearing"	SDM	No	N/A	Extract Data Electronically from SDM	Link	Link	0.001	CLASS	N/A	Becomes major influence EC to SDM to extract data from SDM. The operator would need to manually adjust the data.	
16	Builder angle	Area 2	Degrees	0..1	Fast	New	Autobit	No	N/A	See Comment	Link	Link	Depress.	Link	N/A	ON-Circuitous EC-2 can incorporate a digital output that controls the trim limit on the Propulsion Motor via Interface Board PTM/Rack 3 in the SCC.	
17	IMU	Area 2	RPM	1	Fast	New	OMC	No	N/A	See Comment	Link	Link	Rev/Min	0.1	CLASS	N/A	The Trim Limit on the Propulsion Motor via Interface Board PTM/Rack 3 in the SCC.
18	Ownship depth	Area 2, Area 3	Meters	1	Fast	New	GCS	No	N/A	CCS, UNICAST, Ownership Message Primary Method CCS Ethernet Switch (A1A5) located on the back of CCS Consoles Secondary Standard Method Ethernet Switch located on the back of CCS Consoles, connected to LAN1 Ethernet Switch located next to SDM.	Seconds	Seconds	Freq	0.001	CLASS	N/A	This Ownship Depth is transmitted via UNICAST to a determined IP address. This data would be available within a 32-bit IP address number.
19	Ownship depth/limit/restriction	Area 2, Area 7	Meters	1	Fast	New	NDOS	Yes	N/A	Will require info type for ownership depth.	Seconds	Seconds	Meters	0.001	CLASS	N/A	Primary Method Ownership Message Secondary Standard Method Connect to LAN1 Switch.
20	Depth value for top of depth bracket	Area 2, Area 7	Meters	1	Fast	New	ID Control Inpt	No	N/A	Fixed Input in ID or Manual Input	As Required	As Required	Meters	0.1	CLASS	N/A	This will be a fixed value set at a depth of 0 Meters.
21	Salvage depth limit	Area 2, Area 7	Meters	1	Fast	New	ID Control Inpt	No	N/A	Manual Input	As Required	As Required	Meters	0.1	CLASS	N/A	The Salvage Depth Limit must be determined by Command and Control and stored into the ID. The Safe Depth Limit and last message set commands.
22	Planned Route/wpln: Planned Speed w.r.t water mass	Area 2	Meters	1	Link	New	Command Inpt	No	N/A	Manual Input	As Required	As Required	Meters	0.1	CLASS	N/A	Requires single software EC to SDM to extract data from SDM and move forward to move to manually extract the data.
23	Planned Route/wpln: Maximum Speed	Area 2	Knots	0..1	State Change	New	SDM	No	N/A	Extract Data Electronically from SDM	Link	Link	Knots	0.1	CLASS	N/A	The Ownship Speed is transmitted via UNICAST to a determined IP address. This data would be available in the Ownership Message which identifies the "Speed" within a 32-bit IP address number.
24	Ownship Speed w.r.t. Water Mass	Area 2	Knots	0..1	State Change	New	CCS	No	N/A	CCS, UNICAST, Ownership Message Primary Method CCS Ethernet Switch (A1A5) located on the back of CCS Consoles Secondary Standard Method Retrieve data from LAN1 Ethernet Switch located next to SDM.	Seconds	Seconds	Yards/Second	0.001	CLASS	N/A	The Ownship Speed can be obtained by connecting directly to the R44 Ethernet Switch (A1A5) on the back to the CCS Consoles at 100 MB/sec.
25	Planned Speed	Area 2	Knots	0..1	State Change	New	SDM	No	N/A	Manual Input	Link	Link	Knots	0.1	CLASS	N/A	The Ownship Speed is transmitted via UNICAST to a determined IP address. This data would be available in the Ownership Message which identifies the "Speed" within a 32-bit IP address number.
26	Speed value at top of speed bracket graphic	Area 2	Knots	0..1	State Change	New	ID Control Inpt	No	N/A	Manual Input	As Required	As Required	Knots	0.1	CLASS	N/A	The Ownship Speed is transmitted via UNICAST to a determined IP address. This data would be available in the Ownership Message which identifies the "Speed" within a 32-bit IP address number.
27	Speed value at bottom of speed bracket graphic	Area 2	Knots	0..1	Fast	New	ID Control Inpt	No	N/A	Manual Input	As Required	As Required	Knots	0.1	CLASS	N/A	The Ownship Speed is transmitted via UNICAST to a determined IP address. This data would be available in the Ownership Message which identifies the "Speed" within a 32-bit IP address number.
28	Cavitation Speed	Area 2	Knots	0..1	Fast	New	Command Inpt	No	N/A	Manual Input	As Required	As Required	Knots	0.1	CLASS	N/A	The Ownship Speed is transmitted via UNICAST to a determined IP address. This data would be available in the Ownership Message which identifies the "Speed" within a 32-bit IP address number.
29	Telegraph	Area 2	Position State	0..1	Fast	New	SDM	No	N/A	Manual Input from Sound Room	As Required	As Required	Knots	0.1	CLASS	N/A	The Ownship Position is transmitted via UNICAST to a determined IP address. This data would be available in the Ownership Message which identifies the "Latitude and Longitude" within a 32-bit IP address number.
30	Groupers switch	Area 2	Position State	0..1	Fast	New	OMC	No	N/A	See Comment	Link	Link	State	UNCLASS	N/A	There is currently no simple way of extracting the data directly from the OMCI without retransmitting an EC.	
31	Ownship position	Area 2, Area 4	N/A	Position State	0..1	Fast	OMC	No	N/A	See Comment	Link	Link	State	UNCLASS	N/A	The Ownship Position is transmitted via UNICAST to a determined IP address. This data would be available in the Ownership Message which identifies the "Latitude and Longitude" within a 32-bit IP address number.	
							GCS	No	N/A	CCS, UNICAST, Ownership Message Primary Method CCS Ethernet Switch (A1A5) located on the back of CCS Consoles Secondary Standard Method Retrieve data from LAN1 Ethernet Switch located next to SDM.	Seconds	Seconds	Degress/MilliSeconds	0.0001	CLASS	N/A	Primary Method: Ownship Position can be obtained by connecting directly to the R44 Ethernet Switch (A1A5) on the back of CCS Consoles at 100 MB/sec.
							NDOS	Yes	N/A	NDOS	Seconds	Seconds	Degress/MilliSeconds	0.0001	UNCLASS	N/A	Secondary Method: Connect to LAN1 Switch.
													Low				

Properties of Information for ID											Properties of Required ID Information in the Subsuming System(s) in Which It Is Available							
No.	ID Info Definition	ID Display Ref (Area)	Units	Resolution	Allowed Staleness	Comment	Submarine System	Pub/Sub Topic Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Time Between Data Batches from System With ID	Update Rate of Info Sent From System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment
32	Drown my traces	Area 3	Unk	Unk	Unk													
33	Drown my traces simulated my traces associated with a simulated depth	Area 3	Unk	Unk	Unk													
34	Contact COI range environment prediction	Area 3	Unk	Unk	Unk	In this context COI range is a "predicted" value (e.g. based on manual inputs from sounder, not necessarily from computed data, i.e., TMA) (SFCS)												
35	Incertitude of current contact COI range	Area 3	Nautical Miles	0 - Unk	Unk	Consequently, it will be manifested separately from the original similarity named info types in Area 3-Ref Reg, Area 5-Ref Big Area 5-Weapons, but where the ID is a Contact COI range, it will be manifested from the original similarity named info types in Area 3-Ref Reg, Area 5-Ref Big Area 5-Weapons and also from the SFCS. However this is presumably the uncertainty in the COI range prediction (see preceding info type), which is not SFCS data	Command Input	No	NA	Manual Input from Sound Room	As Required	As Required	Yards	0.1	CLASS	NI	NA	
36	Contact COI range traces	Area 3	Nautical Miles	Unk	Unk	New.	Command Input	No	NA	Manual Input from Sound Room	As Required	Yards	100	CLASS	NI	NA	NA	
37	Contact COI depth	Area 3	Meters	1 - Unk	Unk	Consequently, it will be manifested from the original COI range document, but also from the original depth document. In this instance, Category is intended:	Command Input	No	NA	Manual Input from Sound Room	As Required	Yards	100	CLASS	NI	NA	NA	
38	Contact COI Altitude	Area 3 - Ref Reg, Area 4 - Ref Reg, Area 5 - Ref Reg, Area 6 - Contact Mgt	2 Letter Designator	N/A	Unk	New.	CCS	No	NA	CCS UNICAST - Threat Message	When New Data is Entered	Minute	NA	CLASS	NI	NA	NA	
39	Contact COI Category	Area 3 - Area 4, Area 5 - Ref Reg, Area 6 - Contact Mgt	2 Letter Designator	N/A	Unk	New	CCS	No	NA	CCS UNICAST - Threat Message	When New Data is Entered	Minute	NA	CLASS	NI	NA	NA	
40	Contact COI Platform	Area 3 - Area 4, Area 5 - Ref Reg, Area 6 - Contact Mgt	2 Letter Designator	N/A	Unk	New.	CCS	No	NA	CCS UNICAST - Threat Message	When New Data is Entered	Minute	NA	CLASS	NI	NA	NA	
41	Contact COI Flag	Area 3 - Area 4, Area 5 - Ref Reg, Area 6 - Contact Mgt	2 Letter Designator	N/A	Unk	New. Included in Virtual VIC Data Model; not clear if used in ID.	CCS	No	NA	CCS UNICAST - Threat Message	When New Data is Entered	Minute	NA	CLASS	NI	NA	NA	
42	Track numbers	Area 3 - Area 4, Area 5 - Ref Reg, Area 6 - Contact Mgt	2 Letter Designator	N/A	Unk	Consequently, it will be manifested from the original track number document.	Command Input	No	NA	Manual Input from Sound Room	As Required	As Required	NA	CLASS	NI	NA	NA	
43	Sound velocity profile (SVP) of water	Area 3	Sig Alpha Omega Identifier	Unk	Unk	New.	CCS	No	NA	CCS UNICAST - Threat Message	When New Track Assigned	Minute	NA	CLASS	NI	NA	NA	

Properties of Information for ID											Properties of Required ID Information in the Subsuming System(s) in Which It Is Available							
No.	ID Info Definition	ID Display Ref (Area)	Units	Resolution	Allowed Slateness	Comment	Submarine System	Publsh Subscrpt Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Time Between Data Received From System With ID	Update Rate of Info Sent From System Within System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment
44	Chorded depth	Area 3, Area 7	Unk	Unk	Unk	Bathy	No	N/A	Mk6f BathThermograph	When New Data Received	Depth = End SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
45	Time license of BATHY data	Area 3	Meters	Unk	Unk	A Priori	No	N/A	Download Reference to ID	Unk	Meters	0.1	UNCLASS	N/A	N/A	The SVP Time Latency can be inferred via UNCAST in the Bathy Message. This message provides us Update Distance for update.		
46	Time license of BATHY zones (CZ)	Area 3	Unk	Unk	Unk	Bathy	No	N/A	Mk6f BathThermograph	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
47	Sound channels	Area 3	Unk	Unk	Unk	Bathy	No	N/A	CCS UNICAST - Bathy Message	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	High	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
48	Shadow zones	Area 3	Unk	Unk	Unk	Bathy	No	N/A	Mk6f BathThermograph	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
49	Water temperature	Area 3	Unk	Unk	Unk	Bathy	No	N/A	CCS UNICAST - Bathy Message	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	High	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
50	Thermoclines	Area 3	Unk	Unk	Unk	Bathy	No	N/A	Mk6f BathThermograph	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
51	Bottom contours	Area 3, Area 4	Unk	Unk	Unk	Bathy	No	N/A	Mk6f BathThermograph	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
52	Bottom bathymetric soundspeed	Area 3	N/A	Unk	Unk	CCS	No	N/A	Download Reference to ID	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
53	Transmit oblique soundcasts	Area 3	N/A	Unk	Unk	Bathy	No	N/A	Download Reference to ID	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol. The Serial ASCII modes are based on NIDS protocol.		
54	Best Elevation Depth	Area 3	-	Meters	Unk	Command Input	No	N/A	Manual Input from Sound Room	As Required	As Required	Meters	0.1	CLASS	N/A	N/A	New requires "Best depth for coverages" in Area 3. Not applicable to Area 3.	
55	Best Listening Depth	Area 3	Meters	Unk	Unk	Command Input	No	N/A	Manual Input from Sound Room	As Required	As Required	Meters	0.1	CLASS	N/A	N/A	The Best Listening Depth is determined by the SVP and the resulting Ray Traces.	
56	Tidal current information	Area 3, Area 4, Area 5, Rel Brdg	Meters	Unk	Unk	Command Input	No	N/A	Download Reference to ID	Unk	Unk	Unk	UnCLASS	N/A	N/A	The Best Listening Depth is determined by the SVP and the resulting Ray Traces.		
57	Inventory of hydroacoustic, location and range of critical features	Area 3, Area 5	Time (hrs.)	Unk	Unk	Command Input	No	N/A	Download Data into ID	As Required	As Required	N/A	UNCLASS	N/A	N/A	This is the uncertainty of depth.		
58	Acoustic test state	Area 3	N/A	Unk	Unk	Command Input	No	N/A	Download Data into ID from 4 - 6 hours from Last Log	As Required	As Required	N/A	CLASS	N/A	N/A	The Actual Sea State will be affected by the weather conditions, depth of water, shipping traffic, distance from shore and biological. The range prediction software will provide the Acoustic Test State along with Senior Sourcer Operator's Judgmental input.		
59	Time of next BATHY firing	Area 3, Area 6	N/A	Unk	Unk	Assume this is data from Mk6f Bathy Data Model, New, all per V/H/IC Data Model.	No	N/A	Download Data into ID from 4 - 6 hours from Last Log	As Required	As Required	N/A	UNCLASS	N/A	N/A	The Sound Velocity Profile is transmitted via UNCAST to a designated IP address. The interface is a 6-bit register. The data is sent in binary format. The data includes the time for the message was recorded, Lat/Long of where the data was obtained, filename, probe type and the terminal depth.		
60	Utility data	Area 3	N/A	Unk	Unk	CCS	Yes	N/A	CCS UNICAST - Bathy Message	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	High	Note: Bathy profiles are currently entered into CCS manually, via the transmit interface to CCS via Mk6f BathThermograph and Sound Room.		
						Bathy	No	N/A	Mk6f BathThermograph	When New Data Received	Depth = f feet SV = Feet/Sec	1	CLASS	N/A	Low	The Bathy connection is not currently connected onboard. The Mk6f Bathy message transmits via Serial Binary modes and Serial ASCII modes. The Serial Binary modes are based on NTDS protocol.		

Properties of Information for ID										Properties of Required ID Information in the Subsuming System(s) in Which It Is Available									
No.	ID Info Definition	ID Display Ref (Area)	Units	Resolution	Allowed States/ness	Comment	Subsuming System	Pub/Sub Topic Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Time Between Data From System With System	Update Rate of Info Sent From System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment	
61	Drownship position	Area 4 - Area 2				Pos of Lat/Long	GCS	No	N/A	CCS UNICAST - Ownership Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Retrieve data from LAN1 Secondary Method: Broadcasted to SDM. Method Input	Seconds	Decimal Degrees	0.0001	CLASS	N/A	N/A	The Ownship Position is transmitted via UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit location port number and Longitude" within a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The UNICAST is available at 100 Mbps. The		
62	Drownship course to steer	Area 4				Decimal Degrees	NDDS	Yes	N/A	CCS UNICAST - Ownership Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Retrieve data from LAN1 Secondary Method: Broadcasted to SDM. Method Input	Seconds	Decimal Degrees	0.0001	CLASS	N/A	N/A	The Persistence Out can be identified via UNICAST in the Persistence Message. This is valid for both Seven and Attitude/Precise.		
63	Drownship position: Verification points of path	Area 4 - Area 4				Confirmed points from periscope or GPS	CCS	No	N/A	CCS UNICAST - Periscope Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Broadcasted to SDM.	As Required	As Required	0.1	CLASS	N/A	N/A			
64	Periscope cuts					Requires periscope bearing cuts and Lat/long position (and ID) of the actual OS position fix. New: Record periscope cuts used in position fix.	SDM	No	N/A	CCS UNICAST - Ownership Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Broadcasted to SDM.	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Course to Steer Method is UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The course is available at 100 Mbps. The	
65	Lat/Long position of reference points					Decimal Degrees	0.0001	Link	Link	CCS UNICAST - Periscope Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Broadcasted to SDM.	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Speed is transmitted via UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Heading within a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
66	Drownship Speed w.r.t. Ground	Area 4				Decimal Degrees	0.0001	Link	Link	CCS UNICAST - Ownership Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Broadcasted to SDM.	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Course to Steer Method is UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
67	Drownship Speed w.r.t. Ground	Area 4				Degrees	1	Fast	CCS	CCS UNICAST - Ownership Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Broadcasted to SDM.	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Speed is transmitted via UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Heading within a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
68	Planned route w.r.t. Ground	Area 4				Knots	0.1	Fast	CCS	CCS UNICAST - Ownership Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Broadcasted to SDM.	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Course to Steer Method is UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
69	Contact COI Position	Area 4				Degrees	1	Link	CCS	CCS UNICAST - Ownership Message Primary Method: CCS Ethernet Switch (A/TAS) Secondary Method: Broadcasted to SDM.	Extract Data Electronically from SDM	Link	Link	Link	Link	N/A	N/A	The Ownship Course to Steer Method is UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
70	Contact COI Course w.r.t. Ground	Area 4				Decimal Degrees	0.0001	Link	CCS	CCS UNICAST - Ownership and Threat Messages	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Course to Steer Method is UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
71	Contact COI Speed w.r.t. Ground	Area 4				Degrees	1	Link	CCS	CCS UNICAST - Threat Message	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Course to Steer Method is UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
72	Contact COI track history	Area 4				Knots	0.1	Link	CCS	CCS UNICAST - Threat Message	Manual Input	Link	Link	Link	Link	N/A	N/A	The Ownship Course to Steer Method is UNICAST to a determined IP address. This data would be available to the receiving system via a 32-bit bearing number. Ownership Position is update to the A/TAS Switch and CCS 876 via RUD5 Ethernet at 100 Mbps. The Speed is available at 100 Mbps.	
	Contact COI information: Categories	Area 4 - Area 3				Decimal Degrees	Link	Link	CCS	Historical Record of CCS UNICAST data sent to ID	Historical Record of CCS UNICAST data sent to ID	Link	Link	Link	Link	N/A	N/A	The CCS UNICAST Threat Message Data will provide a continuous feed for the ID to utilize or store. As this data is received and stored in the ID, it can be used to provide a historical perspective.	
73	Location of land	Area 4 - Area 3					A Priori	No	N/A	Download Data in ID	Download Data in ID	Link	Link	Link	Link	N/A	N/A		
74	Coastal areas	Area 4 - Area 3					A Priori	No	N/A	Download Data in ID	Download Data in ID	Link	Link	Link	Link	N/A	N/A		
75	Incentivized about contact COI position	Area 4 - Area 3					Link	Link	N/A	Uses Lat/Long/Depth from EOPNS	Impress info from sensor.	Link	Link	Link	Link	N/A	N/A		
76	Contact COI contact detection ranges	Area 4 - Area 5					0	Link	N/A	Link	Link	Link	Link	Link	Link	Multiple Yards	Yards	Yards	The COI Counter Detection Range will depend upon the SVP and type of CO (ie. Warplane/Helo/Aurora/Fixed Wing Aircraft). The type of vessel abilities will affect the counter detection ranges.
77	Contact COI weapons ranges and types of weapon	Area 4 - Area 5					0.1	Link	N/A	CCS UNICAST - Threat Message	Minutes	Link	Link	Link	Link	100	CLASS	N/A	
	Contact COI weapons ranges and types of weapon	Area 4 - Area 5					COL	No	N/A	Manual Input from Sound Boom	As Required	Yards	Yards	Yards	Yards	100	CLASS	N/A	
	Contact COI weapons ranges and types of weapon	Area 4 - Area 5					COL	No	N/A	Download Data in ID	As Required	Yards	Yards	Yards	Yards	100	CLASS	N/A	This information will be determined by the inputted reference material such as Juries Fighting Ships.

Properties of Information for ID											Properties of Required ID Information in the Subsuming System(s) in Which It Is Available							
No.	ID Info Definition	IIE Display Ref (Area)	Units	Resolution	Allowed Staleness	Comment	Submarine System	Pub/Sub Topic Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Date Between Subsuming System and ID	Update Rate of Info Sent From System Within System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment
78	Currents	Area 4 - Area 5- Rel Brdg	Link	Link	A Priori	No	N/A	Download Data ID	Link	Link	Link	Link	Link	Link	UNCLASS	N/A	N/A	
	Total current information	Area 4 - Area 3- Rel Brdg	Link	Link														
79	Total chart information	Area 4 - Area 4	DTS	Link	A Priori	No	N/A	Download Data ID	Link	Link	Date	N/A	UNCLASS	N/A	N/A	N/A	N/A	
80	Area 4 - Area 4 has been uncrossed from	Area 4	Link	Link														
81	Total routes	Area 4 - Area 4	N/A	Link	A Priori	No	N/A	Download Data ID	Link	Link	Time/Date/Unit	N/A	UNCLASS	N/A	N/A	N/A	N/A	
82	Tactical routes segmentation schemes (TSS)	Area 4 - Area 4	N/A	Link	Commanded Input	No	N/A	Manual Input	As Required	As Required	Unit	N/A	UNCLASS	N/A	N/A	The Trip Wires will be determined by the CO.	N/A	
83	Contract route projection	Area 4 - Area 4	Decimals	Time	New_Projected Track, all suggested by Virtual VC Model, but not clear if actuality used in ID.	CCS	No	Download Data ID	Link	Link	Multiple Yards, Yards/Sec.	N/A	UNCLASS	N/A	N/A	N/A	N/A	
84	Contact altitude	Area 4 - Area 4	Feed	Link	New_Alitude_of_contact, all suggested by Virtual VC Data Model, but not clear if No Alitude is needed this is the feed centre of the ID.	None	No	See Commitment	N/A	N/A	Meters	0.1	CLASS	N/A	N/A	N/A	N/A	
85	Overall position	Area 5 - Rel Brdg	Decimal Degrees	0.0001	Fast	CCS	No	CCS UNICAST - Oceanic Message	Seconds	Degrees	0.00001	CLASS	N/A	N/A	N/A	N/A	N/A	
86	Battery Endurance (gained)	Area 5 - Rel Brdg	Hours	0.1	Show													
87	Battery Endurance (current)	Area 5 - Rel Brdg	Hours	0.1	Show													
88	Drownship signature profile: Range of most detectable signatures (strongest signature)	Area 5 - Rel Brdg	Nautical Miles	0.1	Show													
89	Closest acceptable distance	Area 5 - Rel Brdg	Nautical Miles	0.1	Link	We need to identify multiple potential signature profiles that are dependent on situation (e.g., dived, snorkeling, firing, etc.), and identify how the situation is to be specified to detect the profile.												
90	Depth bracket	Area 5 - Rel Brdg	Meters	1	Link	Look at recommendations for better measurement/prediction of self/noise for VCS.												
		Contact COI center/deciml image	Area 5 - Rel Brdg	0.1	Link	Sets to be different from Area 2 - Area 2 is displayed as a "true bearing" (i.e., no bearing angle), while Area 1 is displayed as a "relative bearing" (i.e., bearing angle relative to the user's current position).												
91	Contact COI weapons range and spec of weapon	Area 5 - Rel Brdg	Nautical Miles	0.1	Link	Commanded Input	No	Manual Input from Sound Room	As Required	As Required	Yards	100	CLASS	N/A	N/A	N/A	N/A	
		Contact COI classification	Area 5 - Rel Brdg	0.1	Link	Commanded Input	No	Manual Input	As Required	As Required	Yards	100	CLASS	N/A	N/A	N/A	N/A	
92	Uncertainty of current contact COI range	Area 5 - Rel Brdg	Nautical Miles	0.1	Link	Reference Library	No	Manual Input	As Required	As Required	Yards	0.1	CLASS	N/A	N/A	N/A	N/A	
93	Contact COI relative location	Area 5 - Rel Brdg	Nautical Miles	0.1	Link	Assume that in the uncertainty in the contact COI range determined from sensor data/IMU.												
94	Contact COI range estimate	Area 5 - Rel Brdg	Nautical Miles	0.1	Link	Node/Batt ID is using a "Relative" bearing, but it's bearing info it uses is normally referred to as "True bearing", i.e., bearing w.r.t. true North.	CCS	No	CCS UNICAST - Threat Message	Minutes	Yards	0.001	CLASS	N/A	N/A	N/A	N/A	
95	Closest point of approach (CPA) Predicted	Area 5 - Rel Brdg	Nautical Miles	0.1	Link	Separate from related info type in Area 3 (COI predicted range).	CCS	No	CCS UNICAST - Threat Message	Minutes	Even 6 Seconds	0.001	CLASS	N/A	N/A	N/A	N/A	
96	Time to CPA	Area 5 - Rel Brdg	Seconds	1	Link	Source specified as ECFINS in Design Doc (not yet implemented). Since historical data should be the same source, which was FCS. Historical data will likely be taken as an accumulation of current range estimate data, so we not be a separate information type (i.e., requiring a different source, e.g., historical database).	CCS	No	CCS UNICAST - Multiple Measures	Various	Nautical Miles	0.1	CLASS	N/A	N/A	N/A	N/A	

Properties of Information for ID											Properties of Required ID Information in the Subsuming System(s) in Which it is Available						
No.	ID Info Definition	IID Display Ref (Area)	Units	Resolution	Allowed Staleness	Comment	Submarine System	Publsh Subscr Done	Transmission Format	Potential Methods to Transfer Info to ID	Time Between Update Rate of Info Sent From System Within System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment
97	Prev via Sensor fixes	Area 5 - Rel Rng	Unk	Unk	Unk	Should be referred to Contact Sensor/TMA	ID History Database	No	NA	CCS UNICAST - Sensor Messages	Minutes	Minute	Multiple Yards, Yards/Sec, Yards/Sec	CLASS	N/A	N/A	The ID would read and process the CCS Sensor Messages to determine the previous sensor fixes.
	Contact CO symbol classification (Alliance, Category, Immunity)	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	Unk	New ID Display documents through the Area 5 Range fixer has NO CO ambiguity or the contact/COI, which will require classification date to choose appropriate symbol											
	Contact CO symbol status (COI course w.r.t. vessel, contact CO speed w.r.t. vessel, contact CO bearing w.r.t. vessel)	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	Unk	New ID Display documents through the Area 5 Range fixer has a velocity vector, area part of the contact/COI symbol, which will require contact/COI course & speed of rel/r/t, water mass info.											
	US symbol, OS course w.r.t. water mass, OS speed w.r.t. water mass	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng	Unk	Unk	Unk	Described in All Area 5 Range fixer has a velocity vector, area part of the contact/COI symbol, which will require contact/COI course & speed of rel/r/t, water mass info.											
98	Owning position	Area 5 - Rel Rng	Unk	Unk	0.0001 Fast	Decimal Degrees	CCS	No	NA	CCS UNICAST - Ownership Message	Seconds	Seconds	Decimals	CLASS	N/A	N/A	See item 431.
	Owning ship bearing w.r.t. Water Mass	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng	Unk	Unk	0.1 Unk	Degrees/Min	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	The Contact bearing is transmitted from the MMSI ID to determine the position. This data must be available in the Threat Message, referred as "Bearing Rate". Using a 64-bit double floating point number.
	Contact COI relative true bearing	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng	Unk	Unk	0.1 Unk	Degrees/Min	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	
99	Contact COI bearing rate	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng	Unk	Unk	0.1 Unk	Degrees/Min	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	
	Contact COI range estimate	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng	Unk	Unk	0.1 Unk	Degrees/Min	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	
	Uncertainty of contact COI range	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng	Unk	Unk	0.1 Unk	Degrees/Min	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	
	Cross acceptable distance	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng	Unk	Unk	0.1 Unk	Degrees/Min	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	
100	Raw handoff until	Area 5 - Rel Rng	NA	Unk	Unk	Range of item arc available from Stern Arc Operating Procedures (SOPs)	Manual Data Collection	No	NA	Manual Input from Sound Room	Link	Link	NA	CLASS	N/A	N/A	Direct Path range prediction from the sound room to the sonar system.
101	Optimum maneuver for ranging (e.g. stem axes 1-3 specified)	Area 5 - Rel Rng	Unk	Unk	Unk	Normal 5' Rel Rng	Command Input	No	NA	Manual Input	As Required	As Required	Degress	0.1	CLASS	N/A	
102	Owning detection range/Source ranges	Area 5 - Rel Rng	NA	Unk	Unk	Normal 5' Rel Rng	Command Input	No	NA	Manual Input from Sound Room	As Required	As Required	Yards	0.1	CLASS	N/A	
103	Owning optimum maneuvering/Aquiring TMA	Area 5 - Rel Rng	Unk	Unk	Unk	Normal 5' Rel Rng	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	The ID would receive Ownership Course and Speed via CCS UNICAST and target Course and Speed via CCS UNICAST. The ID would be required to take this course to maneuver to achieve maximum change in Bearing Rate.
104	Contact COI relative true bearing: Radar data	Area 5 - Rel Rng	Unk	Unk	0.1 Unk	Normal 5' Rel Rng	CCS	No	NA	CCS UNICAST - Threat Message	Minute	Minute	Radians/Sec	0.0001	CLASS	N/A	The Contact bearing data is transmitted via CCS UNICAST. The ID would be required to take this course to maneuver to achieve maximum change in Bearing Rate.
105	Contact COI relative true bearing: ESM	Area 5 - Rel Rng	Degrees	0.1 Unk	Normal 5' Rel Rng	Degrees	CCS	No	NA	CCS UNICAST - Radar Annotation Message	When New Data Received	Degress	0.1	CLASS	N/A	N/A	The Contact bearing message is transmitted via CCS UNICAST. The ID would be required to take this course to maneuver to achieve maximum change in Bearing Rate.
	Contact COI weapons ranges and type of weapon	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	0.1 Unk	Degrees	CCS	No	NA	CCS UNICAST - Threat and ESM Message	When New Data Received	Degress or degrees	0.001	CLASS	N/A	N/A	
	Contact COI command/decision images	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	0.1 Unk	Degrees	CCS	No	NA	CCS UNICAST - Threat and ESM Message	When New Data Received	Degress or degrees	0.001	CLASS	N/A	N/A	
	Owning signature profile: Range of most detectable signatures (stunng, ultimata)	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	0.1 Unk	Degrees	CCS	No	NA	CCS UNICAST - Threat and ESM Message	When New Data Received	Degress or degrees	0.001	CLASS	N/A	N/A	
	Initial damage information and currents	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	0.1 Unk	Degrees	CCS	No	NA	CCS UNICAST - Threat and ESM Message	When New Data Received	Degress or degrees	0.001	CLASS	N/A	N/A	
	CPA	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	0.1 Unk	Degrees	CCS	No	NA	CCS UNICAST - Threat and ESM Message	When New Data Received	Degress or degrees	0.001	CLASS	N/A	N/A	
106	CO change (how / when) behavior (transitions)	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	0.1 Unk	Degrees	CCS	No	NA	CCS UNICAST - Threat and ESM Message	When New Data Received	Degress or degrees	0.001	CLASS	N/A	N/A	The CO behavior changes are not determined by a specific submarine system.
	Contact CO symbol classification (Alliance, Category, Immunity)	Area 5 - Rel Rng, Area 4 - Rel Rng, Area 3 - Rel Rng, Area 2 - Contact	Unk	Unk	0.1 Unk	Degrees	CCS	No	NA	CCS UNICAST - Threat and ESM Message	When New Data Received	Degress or degrees	0.001	CLASS	N/A	N/A	

Properties of Information for ID										Properties of Required ID Information in the Subsuming System(s) in Which It Is Available								
No.	ID Info Definition	ID Display Ref (Area)	Units	Resolution	Allowed Staleness	Comment	Submarine System	Publication Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Date Between System & Subsuming System	Update Rate of Info Sent From System Within Subsuming System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment
107	Contact CO symbol contact COI course w.r.t. water mass, contact CO speed w.r.t. water mass	Area 5 - Rel Brg, Area 5 - Rel Rate, Area 5 - Rel Rng				New. ID Design document shows the Area 5 Bearing view has a velocity vector as part of the contact CO symbol, which will require mass. ID Design document shows the Area 5 Bearing view has a velocity vector as part of the CO symbol, which will require CO course & speed (w.r.t. water mass) info.												
108	Periscope imagery; Periscope type	Area 5 - Perisview	N/A	Unk														
109	Direction of periscope	Area 5 - Perisview	N/A	Position Status	Unk													
110	Periscope imagery; Recent and historical imagery	Area 5 - Perisview	Degrees	0.1	Unk	Presumably historical imagery is just a static view of the area, so it is lost source of data. Assume this is intended to be the source of data.	CCS	No	N/A	CCS UNICAST - Periscope Message	When New Data Received	When New Data Received	Radlens	0.001	CLASS	N/A		
111	Track numbers	Area 5 - Big Rate, Area 5 - Contact Mg, Area 8 - Weapons	Degrees	0.1	Unk													
112	COI track in mission documentation	Area 5 - Brg Rate, Area 5 - Rel Rate, Area 5 - Rel Rng																
113	Contact CO true bearing	Area 5 - Big Rate, Area 5 - Rel Rate, Area 5 - Rel Rng	Degrees	0.1	Unk	Assume this is intended to be the last "true bearing". Confirm this is source w.r.t. Water Mass	CCS	No	N/A	CCS UNICAST - Threat Message	Minute	Minute	Radlens	0.001	CLASS	N/A		
114	COI true bearing rate	Area 5 - Big Rate, Area 5 - Rel Rate, Area 5 - Rel Rng	Degrees	0.1	Unk	Confirm this is COI speed w.r.t. Water Mass	CCS	No	N/A	CCS UNICAST - Threat Message	Minute	Minute	Radlens	0.001	CLASS	N/A		
115	Contact COI speed and type of weapon	Area 5 - Big Rate, Area 5 - Rel Rate, Area 5 - Rel Rng, Area 5 - Rel Weapons (COI current course)	Kts/Sec	0	Unk	Confirm this is COI speed w.r.t. Water Mass	CCS	No	N/A	CCS UNICAST - Threat Message	Minute	Minute	Various	0.001	CLASS	N/A		
116	Contact CO track history	Area 5 - Big Rate, Area 5 - Rel Rate, Area 5 - Rel Rng	Various	Unk		Contact CO track history will likely just be an ID database of reported contacts/CO track date (e.g., TMA status), so no new source is involved, i.e., we do not expect to get history track data in Area 5 w.r.t. Water Mass.	ID History Database	No	N/A	Historical Record of CCS UNICAST data sent to ID	Various	Various	Various		CLASS	N/A		
117	Contact CO recent behaviour	Area 5 - Big Rate, Area 5 - Rel Rate, Area 5 - Rel Rng, Area 5 - Rel Weapons (COI current behaviour (suspects))	N/A	Unk														
118	Treat level associated with COI	Area 5 - Brg Rate	Position (Sale)	N/A	Unk													
119	Lucky contacts	Area 5 - Big Rate	N/A	Unk														
120	Journal threat / type of threat	Area 5 - Big Rate	N/A	Unk														

Properties of Information for ID											Properties of Required ID Information in the Subsuming System(s) in Which It Is Available							
No.	ID Info Definition	ID Display Ref (Area)	Units	Resolution	Allowed States/ness	Comment	Submarine System	Pub/Sub Topic Done	Transmission Format	Potential Methods to Transfer Info to ID	Time Between Data From System Within System	Update Rate of Info Sent From System	Units	Resolution	Security Designation	Constraints	Prioritization & Multiple Systems	Comment
118	Uncertainty of Contact (CO) current bearing	Area 5 - Brdg Rate																
119	Sensor (current) display	Area 5	Digital Degrees	0..2	Link													
120	Time of first handover routine	Area 6	Mins	Link	Link	What sensors are displayed (only known sensor or PRS, Range, etc.)? Only waterfall display? One sensor display per sensor? Video or digital feed?	CCS	No	CCS, UNICAST, Threat Message	Minutes	Minutes	0.001	CLASS	N/A	N/A	N/A	Direct video feed from PRS/BSU/246.	
121	Planned route navigation points	Area 6	Discrete	Link	Link	Changes in course w/r/t Ground, and depth	CCS	No	Video feed from PRS/BSU/246	No	No	N/A	CLASS	N/A	N/A	N/A		
122	Where we are - the first artificial locations	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
123	Where we are - the first natural locations	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
124	Mountain ranges	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
125	Mountain ridges	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
126	Mountain ridges	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
127	Mountain ridges	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
128	Mountains	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
129	Mountains	Area 6	Link	Link			Planned Input	No	Command Input	As Received	Link	Link	CLASS	N/A	N/A	N/A		
130	Current task	Area 6	Link	Link			Planned Input	No	Command Input	As Required	Link	Link	CLASS	N/A	N/A	N/A		
131	When to start	Area 6	Link	Link			Planned Input	No	Command Input	As Required	Link	Link	CLASS	N/A	N/A	N/A		
132	Details of touring plan	Area 6	Link	Link			Planned Input	No	Command Input	As Required	Link	Link	CLASS	N/A	N/A	N/A		
133	Time to next BATTY firing	Area 6, Area 3	Meters	1	Fired													
134	Warning depth	Area 7	Meters															
135	Depth threshold	Area 7, Area 2					Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A	The Warning Depth would be entered by Command.		
136	Depth threshold	Area 7, Area 8					Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A	The Warning Depth would be entered by Command.		
137	Other contacts speed, course, bearing: Optimize all contacts by domain	Area 8 - Contact	Link			We assume the user selects an update rate of 100ms or less. If CO is not selected, then we assume the user selects 1000ms or less.	CCS	No	CCS, UNICAST, Threat Message	0.25 Seconds	NA	NA	CLASS	N/A	N/A			
138	CO Classification/Uncertainty of COI classification	Area 8 - Contact	Link			New Virtual Alert has been acknowledged.	ID Control Input	No	Manual Input	As Required	Link	Link	UNCLASS	N/A	N/A			
139	COI classification	Area 8 - Contact	Link			New Virtual Alert has expired. No updates.	ID Control Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
140	COI classification	Area 8 - Contact	Link			CCS, UNICAST, Threat Message	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
141	COI classification	Area 8 - Contact	Link			In what format is uncertainty / classification information provided? Qualitative, discrete continuums, etc.?	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
142	COI classification	Area 8 - Contact	Link			Assume this is just a scatter plot on info already provided to ID.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
143	COI classification	Area 8 - Contact	Link			Uses the reports of Contact Speed, Course & Bearing. Could use reports from Sensors or SF GS.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
144	COI classification	Area 8 - Contact	Link			Assume this is just a scatter plot on info already provided to ID.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
145	COI classification	Area 8 - Contact	Link			Assume this is just a scatter plot on info already provided to ID.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
146	COI classification	Area 8 - Contact	Link			Assume this is just a scatter plot on info already provided to ID.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
147	COI classification	Area 8 - Contact	Link			Assume this is just a scatter plot on info already provided to ID.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
148	COI classification	Area 8 - Contact	Link			Assume this is just a scatter plot on info already provided to ID.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			
149	COI classification	Area 8 - Contact	Link			Assume this is just a scatter plot on info already provided to ID.	Command Input	No	Manual Input	As Required	Link	Link	CLASS	N/A	N/A			

No.	ID Info Definition	Properties of Information for ID				Properties of Required ID Information in the Submitting System(s) in Which It Is Available												
		ID Display Ref (Area)	Units	Resolution	Allowed Staleness	Comment	Submarine System	Pub/Sub Topic Done	Transmission Format	Potential Method(s) to Transfer Info to ID	Time Between Update Rate of Info Sent From System Within System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment	
140	Sensors building contact	Area 8 - Contact Agl	N/A	Unk		There will be a difference between sensors that are receiving data on the contact which would be available very at the sensor level, and sensors that are connected to SFCS. The latter would be much easier to provide an ID, but there would be a way of knowing when SFCS is not receiving reports (e.g., sensor still has contact), but the sensor still has contact.	Command Input	No	N/A	Manual Input - Remote Input from sound comm	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	Information will be provided by Sound Room.
141	Integrated interpretation of COI counted collection masses and ownership signature and integrated interpreted lists of associated with COIs. Show when ownership is in sensor range	Area 8 - Contact Agl	N/A	Unk		Show ownership is in sensor range means when ownership is in range of contacts to determine if it is in project 16 range. If no SFCS is COI, contact is needed to ID, but there would be a way of knowing when SFCS is not receiving reports (e.g., sensor still has contact).	Command Input	No	N/A	Manual Input - Remote Input from sound comm	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	Information will be provided by Sound Room.
142	COI counted collection ranges	Area 8 - Contact Agl	N/A	Unk		Crossing in a weapons range means a weapons range is in range of contact to determine if it is in project 16 range. If no SFCS is COI, contact is needed here to determine when to show, as with Areas 4 Area-Rel Pkg Area 8 Rel Brg, Areas 5 Brg Rate Area 8-COI. Will also need info type for range between CO and CO.	Command Input	No	N/A	Manual Input - Remote Input from sound comm	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	The information would be entered into the ID form generated on source materials.
143	COUNT Show when intelligence available	Area 8 - Contact Agl	N/A	Unk		New To generate the list of COIs	Download Data into ID	No	N/A	As Required	As Required	N/A	N/A	CLASS	N/A	N/A		
144	COIs listed in mission documentation	Area 8 - COI	N/A	Unk		Information type of the preceding item, we will also need the actual "mission documentation". Note that the COI list is sorted (if needed) as to where the contact is CO as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
145	Mission documentation	Area 8 - COI	N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
146	COI Contact	Area 8 - COI	N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	UNCLASS	N/A	N/A	Determined by Command
147	Notes		N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
148	COI Details		N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
149	COI records. Show all library data on a selected COI.	Area 8 - COI	N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
150	COI counted collection ranges	Area 8 - COI	N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
151	Integrated interpretation of COI counted collection masses and ownership signature. Show when ownership is in counted collection range of COI	Area 8 - COI	N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
152	Weather cloud coverage	Area 8 - Weather	N/A	Scale 0-10	Unk	New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	CLASS	N/A	N/A	
153	Weather Wind force	Area 8 - Weather	N/A	Knobs	1 Unk	New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	N/A	N/A	UNCLASS	N/A	N/A	
154	Weather Wind direction	Area 8 - Weather	N/A	Degrees	1 Unk	New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	Destress	1	UNCLASS	N/A	N/A	
155	Visibility	Area 8 - Weather	N/A	Knobs	1 Unk	New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	Yards	0.1	UNCLASS	N/A	N/A	
156	Year sea state	Area 8 - Weather	N/A	Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	Yards	NA	UNCLASS	N/A	N/A	
157	Sunrise/sunset bearing	Area 8 - Weather	Degrees	1 Unk		New Any notes specific to the contact as per Virtual VIC Data Model.	Command Input	No	N/A	Manual Input	As Required	As Required	Degress	1	UNCLASS	N/A	N/A	
158	Moon rising/taking	Area 8 - Weather	Degrees	1 Unk		New Moon visibility (New through Full), as suggested by Virtual VIC Data Model, but not COI.	Manual Input	No	N/A	Manual Data Collection	As Required	As Required	Degress	1	UNCLASS	N/A	N/A	
159	Moon phase	Area 8 - Weather	N/A	Scale 0 - 10	Unk	New Moon's "Phase" or "Waxing/Moving" as suggested by Virtual VIC Data Model, but not COI.	Manual Input	No	N/A	Manual Data Collection	As Required	As Required	N/A	N/A	UNCLASS	N/A	N/A	
160	Moon Ecl	Area 8 - Weather	N/A	Waxing/Moving	1 Unk	New Moon's "Phase" or "Waxing/Moving" as suggested by Virtual VIC Data Model, but not COI.	Manual Input	No	N/A	Manual Data Collection	As Required	As Required	N/A	N/A	UNCLASS	N/A	N/A	
161	Sunrise/inline	Area 8 - Weather	Degrees	1 Unk		New Sun's "Phase" or "Waxing/Moving" as suggested by Virtual VIC Data Model, but not COI.	Manual Input	No	N/A	Manual Data Collection	As Required	As Required	N/A	N/A	UNCLASS	N/A	N/A	
162	Morning/evening minutes/night	Area 8 - Weather	Degrees	1 Unk		New Sun's "Phase" or "Waxing/Moving" as suggested by Virtual VIC Data Model, but not COI.	Manual Input	No	N/A	Manual Data Collection	As Required	As Required	Hour, Min, Sec	Seconds	UNCLASS	N/A	N/A	

Properties of Information for ID												Properties of Required ID Information in the Subsuming System(s) in Which It Is Available						
No.	ID Info Definition	IIC Display Ref (Area)	Units	Resolution	Allowed States/ness	Comment	Submarine System	Publishe Subscrib Done	Transmisson Format	Potential Method(s) to Transfer Info to ID	Time Between Data Befor Sera From System Within System	Update Rate of Info Sera From System	Units	Resolution	Security Designation	Constraints	Prioritization of Multiple Systems	Comment
163	True if information about the external environment we ascribed	Area 8 - Weather	Seconds	1.Urk			Manual Data Collection	No	N/A	As Required	As Required	Hour, Min, Sec	Seconds	UNCLASS	N/A	N/A	The Weapon State Table Number is transmitted via UNICAST to a determined IP address. This data would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
164	Weapon state: Tube Number	Area 8 - Weapons	NA	NA			CCS UNICAST - Set Weapon State Message	No	N/A	When New Data Received	When New Data Received	Tube Number	NA	CLASS	N/A	N/A	The Weapon State Table Number is determined via UNICAST to a determined IP address. This data would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
165	Weapon state: Mod of weapon tube	Area 8 - Weapons	NA	NA			CCS UNICAST - Set Weapon State Message	No	N/A	When New Data Received	When New Data Received	NA	NA	CLASS	N/A	N/A	The Weapon State Table Number is determined via UNICAST to a determined IP address. This data would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
166	Weapon state: Weapon type	Area 8 - Weapons	NA	NA			CCS UNICAST - Set Weapon State Message	No	N/A	When New Data Received	When New Data Received	NA	NA	CLASS	N/A	N/A	The Weapon State Weapon Type is transmitted via UNICAST to a determined IP address. This data would be available in the Tube Inventory Message identified as "Weapon Type" using a 32-bit unsigned integer. The message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer. The value would be available in the Set Weapon State Message identified as "Exercise" using a 32-bit flag. The value identified as "Type" and either Nominal or Exercise Mode.	
167	Weapon state: Count	Area 8 - Weapons	NA	NA			CCS UNICAST - Tube Inventory Message	No	N/A	When New Data Received	When New Data Received	NA	NA	CLASS	N/A	N/A	The Weapon State Weapon Type is transmitted via UNICAST to a determined IP address. This data would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
168	Weapon state: Track number	Area 8 - Weapons	NA	NA		Description implies inventory count of resources, etc; yet be obtained from FCS, but this information is not held by SFCS.	Manual Data Collection	No	N/A	As Required	As Required	NA	NA	CLASS	N/A	N/A	The Weapon State enabling the weapon to be tracked is transmitted via UNICAST to a determined IP address. The message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
169	Weapon state: Weapon enabling	Area 8 - Weapons	NA	NA			CCS UNICAST - Mk48 Mod4 Telecom Message	No	N/A	When New Data Received	When New Data Received	NA	NA	CLASS	N/A	N/A	The Weapon State Weapon Enabling is transmitted via UNICAST to a determined IP address. The message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
170	Weapon state: Weapon Under Control (WUC)	Area 8 - Weapons	NA	NA			CCS UNICAST - Mk48 Mod4 Weapon Readback Message	No	N/A	When New Data Received	When New Data Received	NA	NA	CLASS	N/A	N/A	The Weapon State Weapon Under Control is transmitted via UNICAST to a determined IP address. The message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
171	Weapon state: Status of how many	Area 8 - Weapons	NA	NA			CCS UNICAST - Mk48 Mod4 Weapon Readback Message	No	N/A	When New Data Received	When New Data Received	NA	NA	CLASS	N/A	N/A	The Weapon State Bow Cuts is transmitted via UNICAST to a determined IP address. The message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
172	Weapon state: Status of how bullets	Area 8 - Weapons	NA	NA		This information type is missing from Design doc.	CCS UNICAST - Tube Status Message	No	N/A	When New Data Received	When New Data Received	NA	NA	CLASS	N/A	N/A	The Weapon State Bullet Shatters is transmitted via UNICAST to a determined IP address. This data would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer. The value would be available in the Set Weapon State Message identified as "Shattered" using a 1-bit flag.	
173	Weapon state: Slumbered signal Specter (SS)	Area 8 - Weapons	NA	NA			CCS UNICAST - Tube Status Message	No	N/A	As Required	As Required	NA	NA	UNCLASS	N/A	N/A	The Weapon State Slumbered Signal Specter is transmitted via UNICAST to a determined IP address. The message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
174	Weapon state: Mod of SS	Area 8 - Weapons	NA	NA		ID Design Doc. Indicated as derived from SFCS No current capability to get info from SFCS	Manual Data Collection	No	N/A	As Required	As Required	NA	NA	UNCLASS	N/A	N/A	The Weapon State Mod of SS is transmitted via UNICAST to a determined IP address. This message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
175	Weapon state: Type of item loaded in SS	Area 8 - Weapons	NA	NA			CCS UNICAST - Command Input	No	N/A	As Required	As Required	NA	NA	UNCLASS	N/A	N/A	The Weapon State Type of item loaded in SS is transmitted via UNICAST to a determined IP address. This message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
176	Weapon state: Torpedo limits display (TLD)	Area 8 - Weapons	NA	NA			CCS UNICAST - Mk48 Mod4 Weapon Readback Message	No	N/A	Multiple: Meters, Yards, Kilometers	0.25 Seconds	NA	1 to 1	CLASS	N/A	N/A	The Weapon State Torpedo Limits Display is transmitted via UNICAST to a determined IP address. This message would be available in the Set Weapon State Message identified as "Tuke" using a 32-bit Unicast integer.	
COI true bearing	COI current course	Area 8 - Weapons	NA	NA			CCS UNICAST - Threat Message	No	N/A	Radius	0.001	CLASS	N/A	N/A	N/A	N/A	The Uncertainty of course of COI is transmitted via UNICAST to a determined IP address. This data would be available in the Threat Message identified as "COI Course" using a 32-bit floating point number.	
COI Speed	COI Range Estimate	Area 8 - Weapons	0.1.Urk	0.1.Urk			CCS UNICAST - Threat Message	No	N/A	Minute	NA	CLASS	N/A	N/A	N/A	N/A	The Uncertainty of speed of COI is transmitted via UNICAST to a determined IP address. This data would be available in the Threat Message identified as "COI Speed" using a 32-bit floating point number.	

Properties of Required IID Information in the Submarine System(s) in Which It Is Available

Destination and ETA

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List of symbols/abbreviations/acronyms/initialisms

A-D	Analog to Digital
AIS	Automatic Identification System
BSS	Bathymetric Sampling System
C&PO	Chief and Petty Officer
CCS	Command and Control System
CFB	Canadian Forces Base
CO	Carbon Monoxide
CO	Commanding Officer
CO2	Carbon Dioxide
COI	Contact of Interest
CS	Combat System
CSS	Central Surveillance System
CWA	Cognitive Work Analysis
DGS	Data Gathering System
DND	Department of National Defence
DRDC	Defence Research & Development Canada
EC	Engineering Change
ECPINS	Electronic Chart Precision Integrated Navigation System
ESM	Electronic Support Measures
ETA	Estimated Time of Arrival
FY	Fiscal Year
GFI	Government Furnished Information
GPS	Global Positioning System
IID	Information Integration Display
INS	Inertial Navigation System
IP	Internet Protocol
LAN	Local Area Network
LMC	Lockheed Martin Canada
N/A	Not Applicable

Nav O	Navigation Officer
O2	Oxygen
Op O	Operations Officer
OSN	Ownship Noise
R&D	Research & Development
SDM	SHINNADS Dual Monitor
SHINNADS	Shipboard Integration Navigation and Display System
SV	Sound Velocity
TWS	Tactical Weapon System [Trainer]
Unk	Unknown
VCS	Victoria Class Submarine
w.r.t.	With Respect To